
(i) An approach to real-time wireless networking

(ii) A clean slate approach to a secure wireless network: From axioms to protocols

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ICTW
Maui
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From event-driven to time-driven computation

- ◆ Computers originally developed for computation
 - ENIAC (1946)
- ◆ Real-time computation (1973)
 - Digital control (circa 1960): Computation in feedback loop
- ◆ Hybrid systems (1990s)
 - Interplay of differential equations and logical dynamics
- ◆ Cyberphysical Systems

- ◆ How to support delay guarantees over an *unreliable* medium like wireless?
 - Goal: Formulate a mathematical *framework* for delay-based QoS



Importance of providing latency guarantees: Wireless Tomorrow

- ◆ Current Internet
 - ◆ No guarantees – “Best effort”
 - ◆ At best – Throughput
- ◆ Increasing traffic with delay constraints
 - VoIP
 - Interactive Video
 - Cyberphysical systems
- ◆ How to support delay guarantees over an unreliable medium like wireless?

In-Vehicle Networks

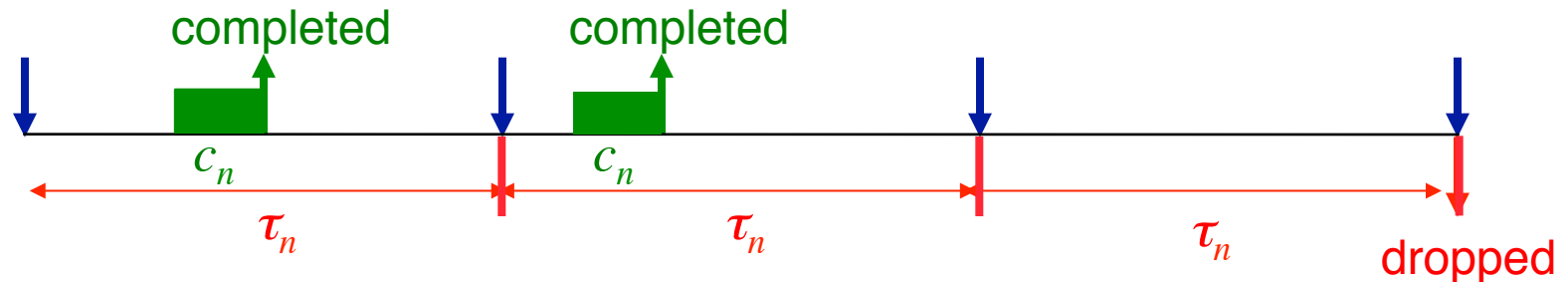
- ◆ Wiring harness
 - ◆ Heavy
 - ◆ Complex
 - ◆ Costly



Replace wires by an access point

- ◆ Fewer mechanical failures
- ◆ Easier to upgrade

Real-Time Scheduling: Liu-Layland ('73)

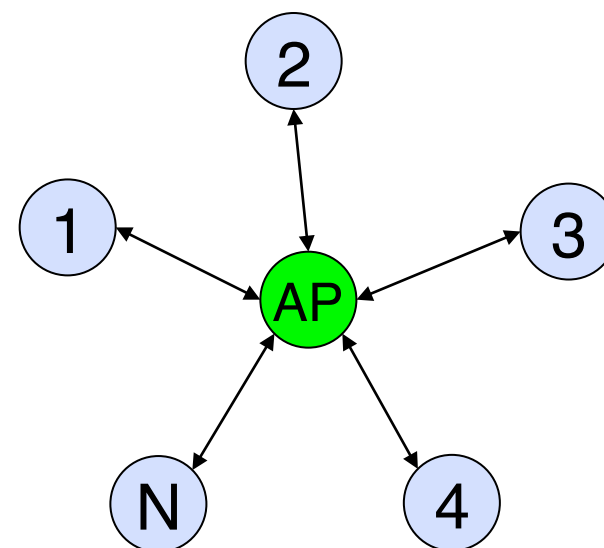
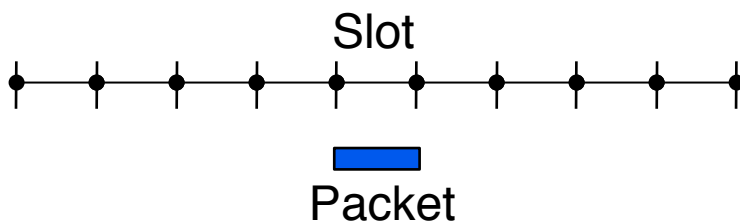


- ◆ N tasks
 - Jobs of Task n arrive with period τ_n
 - Deadline is end of period
 - Worst case execution time c_n
- ◆ Rate monotone scheduling: Priority to smallest period task
- ◆ All deadlines met if
$$\sum_{n=1}^N \frac{c_n}{\tau_n} \leq N(2^{1/N} - 1) \quad (\rightarrow \ln 2 = 0.69 \text{ as } N \rightarrow \infty)$$
- ◆ If any priority policy can meet all deadlines, then this policy can

Real-time communication

Client-Server model

- ◆ A wireless system with an Access Point serving N clients
- ◆ Time is slotted
- ◆ One slot = One packet



- ◆ AP indicates which client should transmit in each time slot

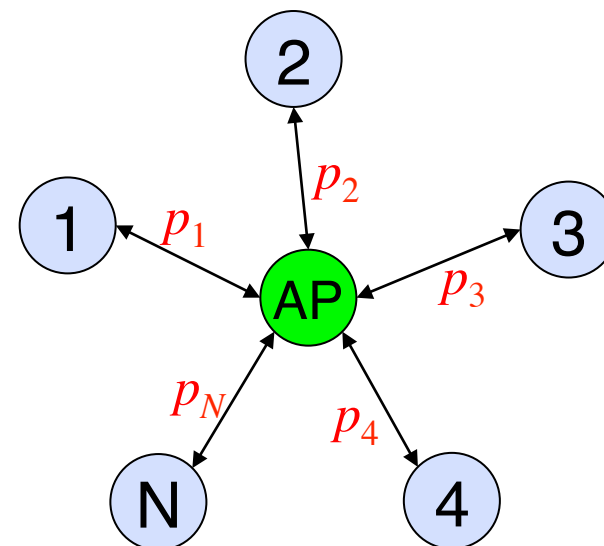
Model of unreliable channels

- ◆ Unreliable channels

- ◆ Packet transmission in each slot

- Successful with probability p_n
- Fails with probability $1-p_n$

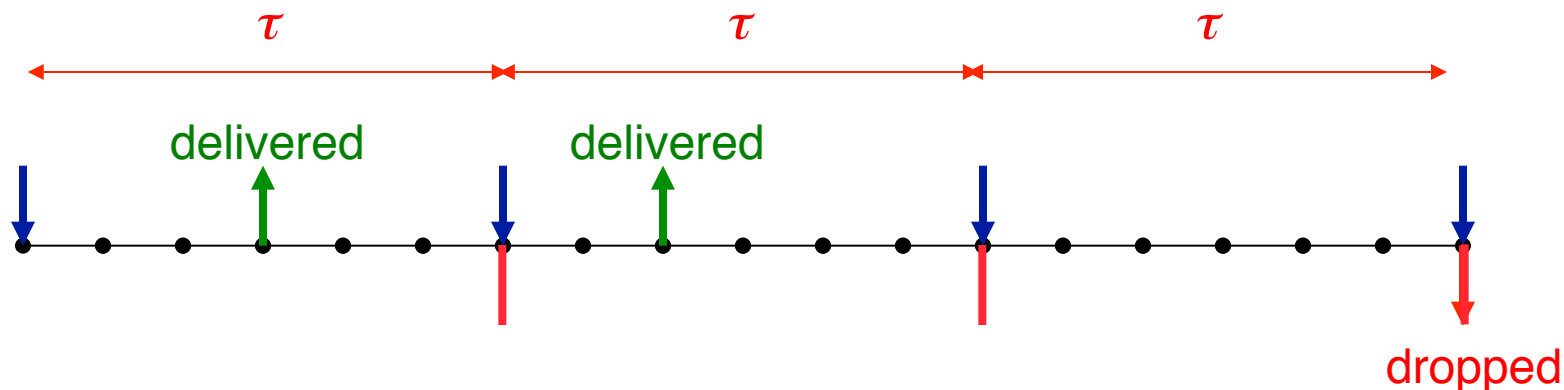
- So packet delivery time is a geometrically distributed random variable γ_n with mean $1/p_n$



- ◆ Non-homogeneous link qualities

- p_1, p_2, \dots, p_N can be different

QoS model

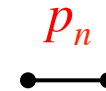


- ◆ Clients generate packets with fixed period τ
- ◆ Packets expire and are dropped if not delivered in the period
- ◆ Delay of successfully delivered packet is therefore at most τ
- ◆ Delivery ratio of Client n should be at least q_n packets/period

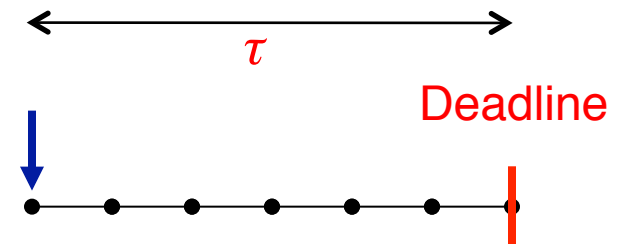
$$\liminf_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T 1(\text{Packet delivered to Client } n \text{ in } t\text{-th period}) \geq q_n \quad a.s.$$

Multiple-time scale QoS requirements

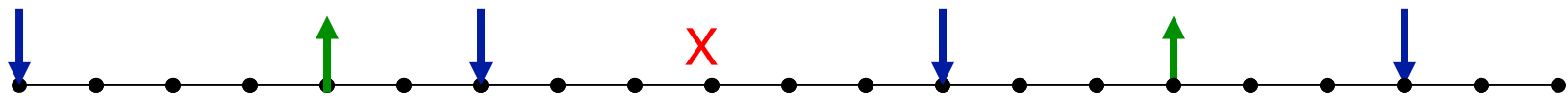
- ◆ Unreliable channels
 - Short time scale: Slots



- ◆ Arrivals and Deadlines
 - Medium time scale:
 - Period τ arrivals
 - Relative Deadline τ



- ◆ Delivery ratio requirements
 - Long time scale:



$$\liminf_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T 1(\text{Packet of client } n \text{ delivered in } t\text{-th period}) \geq q_n \text{ a.s.}$$

Feasibility of a set of clients

Load due to Client n

- ◆ The proportion of time slots needed by Client n is

$$w_n = \frac{E(\# \text{ deliveries per period}) \cdot E(\# \text{ slots per delivery})}{\# \text{ of slots of per period}}$$

$$= \frac{q_n \cdot \frac{1}{p_n}}{\tau}$$

Necessary condition for feasibility of QoS requirements

- ◆ Necessary condition from classical queueing theory

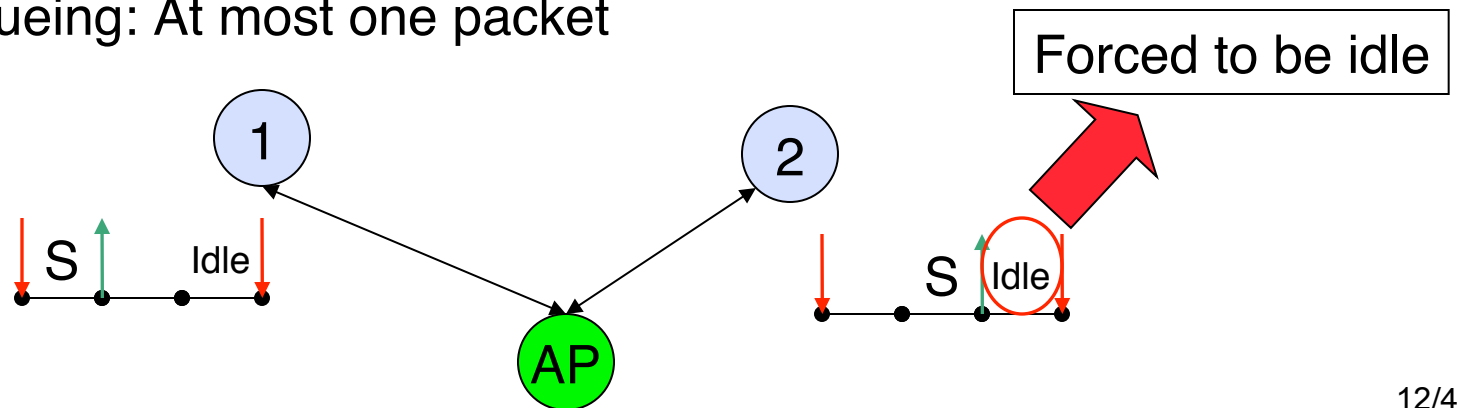
$$\sum_{n=1}^N w_n \leq 1$$

- ◆ Is it sufficient?

- ◆ No

- ◆ Reason: Unavoidable idle time

- No queueing: At most one packet



Stronger necessary condition

- ◆ Let $I(1, 2, \dots, N) :=$ Unavoidable idle time after serving $\{1, 2, \dots, N\}$

$$I(1, 2, \dots, N) = \frac{1}{\tau} E \left[\left(\tau - \sum_{n=1}^N \gamma_n \right)^+ \right] \text{ where } \gamma_n \sim \text{Geom}(p_n)$$

- ◆ Stronger necessary condition

$$\sum_{n=1}^N w_n + I(1, 2, \dots, N) \leq 1$$

- ◆ Sufficient?
- ◆ **Still not sufficient!**

Counterexample

- ◆ Two clients: Period $\tau = 3$

- ◆ Client 1

- $p_1 = 0.5$
- $q_1 = 0.876$

- $w_1 + I_1 = 3.002/3 > 1$ ✗

$$w_1 = \frac{q_1}{p_1 \tau} = \frac{1.752}{3}$$

$$I_1 = \frac{(2p_1 + (1 - p_1)p_1)}{3} = \frac{1.25}{3}$$

- ◆ Client 2

- $p_2 = 0.5$
- $q_2 = 0.45$

- $w_2 + I_2 = 2.15/3 < 1$ ✓

$$w_2 = \frac{q_2}{p_2 \tau} = \frac{0.9}{3}$$

$$I_2 = \frac{1.25}{3}$$


- ◆ Clients $\{1,2\}$

- $w_1 + w_2 + I_{\{1,2\}} = 2.902/3 < 1$ ✓

$$w_{\{1,2\}} = w_1 + w_2 = \frac{2.652}{3}$$

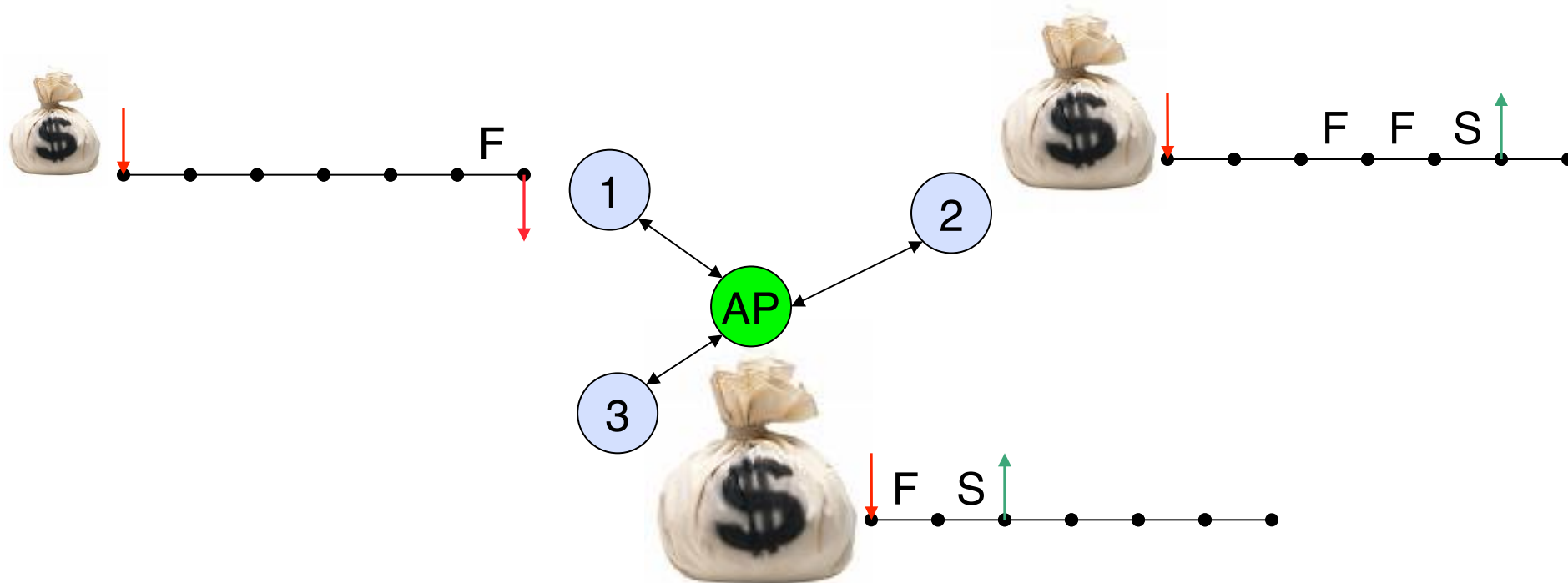
$$I_{\{1,2\}} = \frac{p_1 p_2}{3} = \frac{0.25}{3}$$

Even stronger necessary condition

- ◆ Every *subset* of clients $S \subseteq \{1, 2, \dots, N\}$ should also be feasible
- ◆ Let $I(S) := \frac{1}{\tau} E \left[\left(\tau - \sum_{n \in S} \gamma_n \right)^+ \right]$ = Idle time if only serving S
- ◆ Stronger necessary condition: $\sum_{n \in S} w_n + I(S) \leq 1, \quad \forall S \subseteq \{1, 2, \dots, N\}$

- ◆ Not enough to just evaluate for the whole set $\{1, 2, \dots, N\}$
- ◆ **Theorem (Hou, Borkar & K '09)**
Condition is necessary and sufficient for a set of clients to be feasible

Scheduling policy

Debt-based scheduling policies



- ◆ Compute “debt” owed to each client at beginning of period
- ◆ A client with higher debt gets a higher priority on that period

Two definitions of debt

- ◆ The **time debt** of Client n



$$= (w_n - \text{Actual proportion of transmission slots given to Client } n)$$

- ◆ The **weighted delivery debt** of Client n



$$= \frac{q_n - \text{Actual delivery ratio of Client } n}{P_n}$$

- ◆ **Theorem (Hou, Borkar & K '09)**

Both largest debt first policies fulfill every set of clients that can be fulfilled

Computationally tractable policy for admission control

- ◆ Admission control consists of determining feasibility
- ◆ We need to check: $\sum_{n \in S} w_n + I_S \leq 1, \forall S \subseteq \{1, 2, \dots, N\}$
- ◆ Apparently 2^N tests, so computationally complex, but
- ◆ **Theorem (Hou, Borkar & K '09)**
 - Order the clients according to q_n in decreasing order
 - Then we need only N tests: Check $\{1, 2, \dots, k\}$ for $1 \leq k \leq N$
 - $\{1, 2, \dots, N\}$ infeasible $\Leftrightarrow \sum_{n=1}^k w_n + I(1, 2, \dots, k) > 1$ for some k
 - Polynomial time $O(N\tau \log \tau)$ algorithm for admission control

Utility maximization for elastic traffic

Utility maximization framework

- ◆ Client n has a utility function $U_n(q_n)$
 - U_n positive, str incr, str concave, $U_n(0) =$ right limit ...
- ◆ Maximize the total utility
- ◆ SYSTEM

Max

s.t.
$$\sum_n U_n(q_n)$$

over

$$\sum_{n \in S} \frac{q_n}{\tau p_n} \leq 1 - I_S, \forall S$$

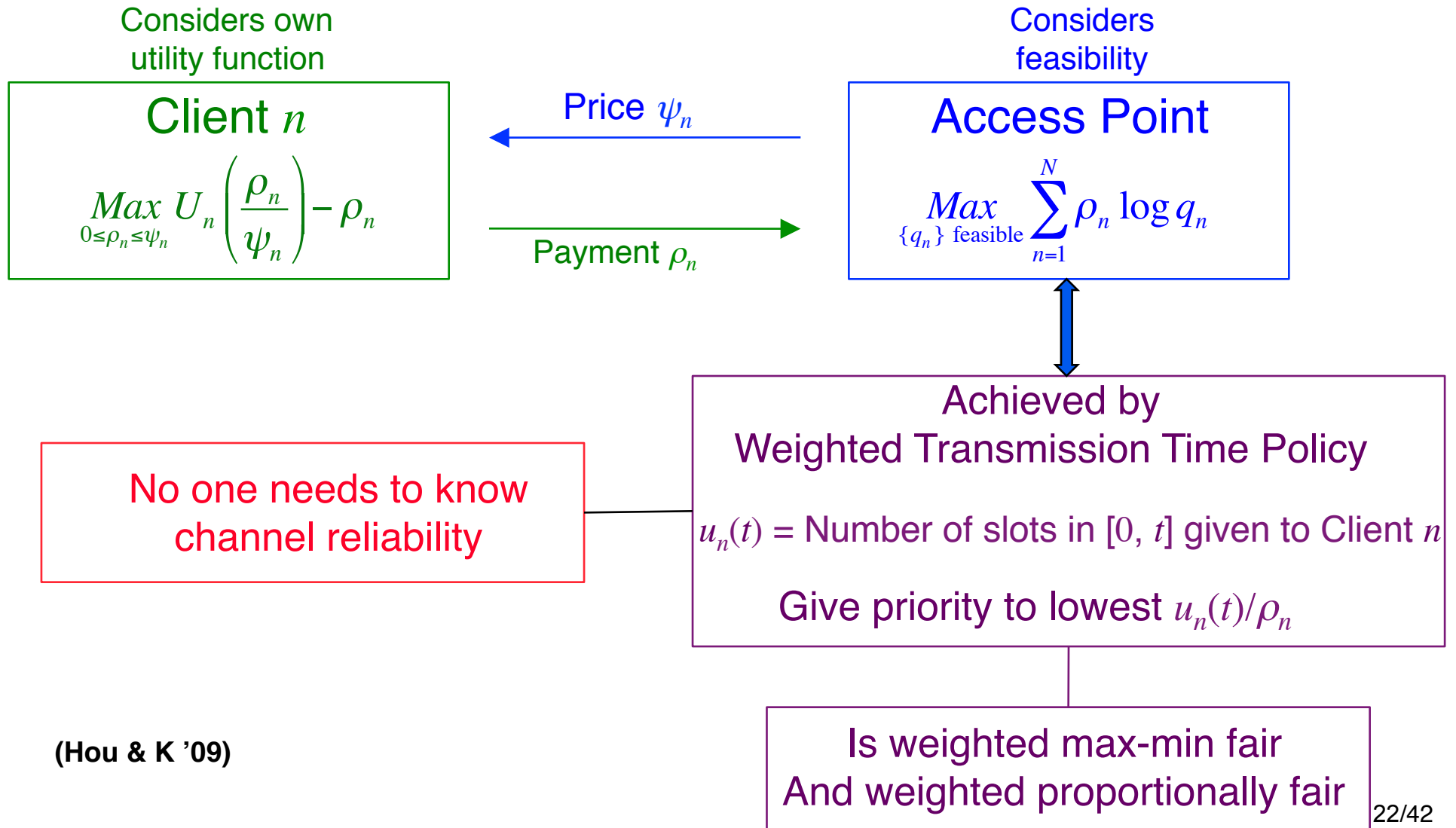
$$q_n \geq 0$$

Solving SYSTEM directly is difficult

Clients may have different utility functions U_n

2^N feasibility constraints

Two sub-problems



Concluding remarks

- ◆ A *framework* for delay-based QoS that encompasses
 - deadlines
 - channel unreliabilities
 - timely throughput
 - client utilities
 - fading channels
 - correlated arrivals
 - rate adaptation
 - minimum throughput requirements,
 - broadcasting (network coding), etc.
- ◆ Analytically tractable
- ◆ Implementable policies
- ◆ Approach to *real-time wireless networking*?

A clean slate approach to a secure wireless network: From axioms to protocols

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Goals

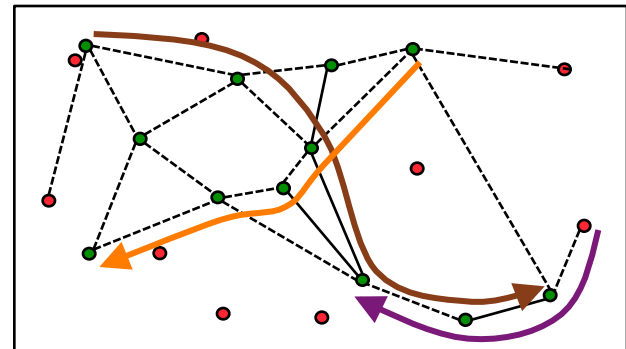
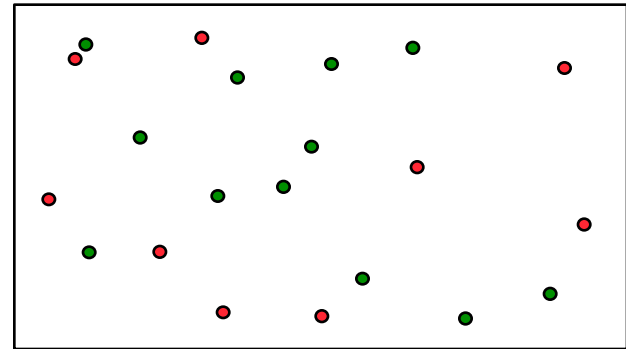
- ◆ Principled approach to security
 - Holistic design of security
 - Security is not an afterthought
- ◆ Security first, performance second
 - Performance subsequently optimized while preserving security
- ◆ Reverse of the usual approach

- ◆ Clean slate design of secure wireless networking
- ◆ Provably secure design
- ◆ Max-Min Optimal
- ◆ Complete suite of algorithms/protocols
- ◆ (Run applications based on temporal coordination)

A lot of explanation is clearly needed ...

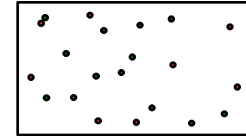
Basic objective

- ◆ A complete suite of algorithms/protocols that takes you
 - ◆ From startup
 - With just a set of nodes
 - Some **good**
 - Some **bad**
 - Good nodes don't know who the bad nodes are
 - ◆ To an optimized functional network carrying data reliably



What can go wrong with a network formed in presence of bad nodes?

- ◆ Some nodes are bad. What can go wrong?



- ◆ Lots of things. A bad node could
 - Refrain from relaying a packet
 - Advertise a wrong hop count
 - Advertise a wrong logical topology
 - Jam
 - Cause packet collisions
 - Behave uncooperatively vis-à-vis medium access
 - Disrupt attempts at cooperative scheduling
 - Drop an “ACK”
 - Refuse to acknowledge a neighbor’s handshake
 - Behave inconsistently

“Byzantine”
behavior

One approach

- ◆ Identify “ATTACKS”
- ◆ Provide “DEFENSES”
- ◆ Result is
 - A sequence of patches
 - Arms race
- ◆ Issue
 - What other attacks are possible?
- ◆ Can we come up with provably secure architecture?
- ◆ Principled design: Holistic approach to security, not afterthought
- ◆ Complete suite of protocols from start-up to reliable operation

Main results

- ◆ Protocols that lead from start-up to functional policed system
- ◆ Resulting network is Min-Max optimal with respect to utility

$$\underset{\text{All behaviors of bad nodes}}{\textit{Min}} \quad \underset{\text{Protocols}}{\textit{Max}} U(x)$$

- ◆ In fact we will show

$$\underset{\text{Bad nodes can choose to either Jam or Cooperate}}{\textit{Min}} \quad \underset{\text{Protocols}}{\textit{Max}} U(x)$$

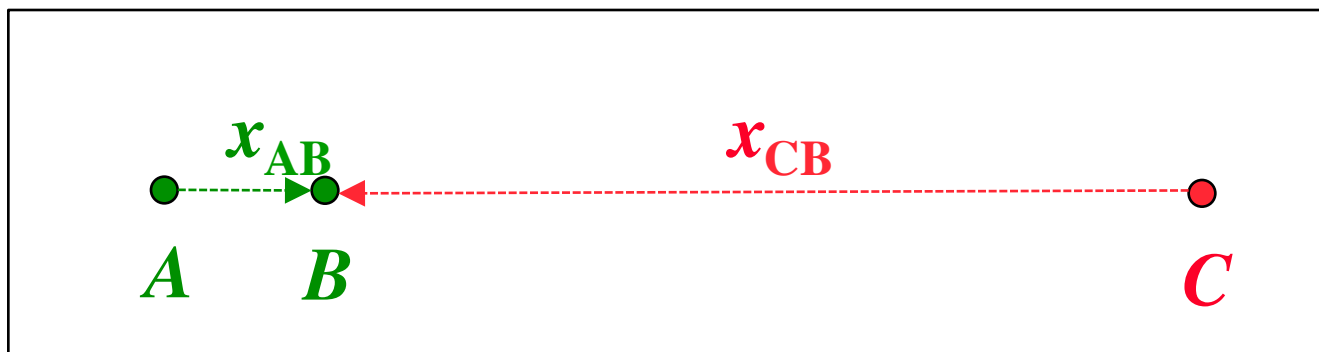
- ◆ Hence, bad nodes are restricted to following actions
 - Either **Jam** or **Cooperate** in a consistent way
- ◆ (Also, timings applications can be consistently run on network)

Implications of results

- ◆ Bad nodes can either choose to **Jam** or **Cooperate**
 - In a way that is consistent for each concurrent transmission set
- ◆ Nobody can prevent **Jamming** or **Cooperating** when it is done in a consistent way
- ◆ Other more malicious behaviors are ruled out
 - Not relaying a packet
 - Dropping an ACK
 - Presenting a wrong logical topological view
 - Disrupt medium access cooperation
 - Disrupt timing applications by inconsistent behavior
 - Not cooperating, disrupting, lying, spreading rumors, etc

Why would a bad node ever cooperate?

- ◆ $U(x) = \text{Min}(x_i)$



- ◆ If **C jams**, it can reduce x_{AB}

$$\lim_{|BC| \rightarrow \infty} x_{AB} = x_{AB}^{Max}$$

- ◆ If **C pretends to be good**, it can insist on equal share

$$\lim_{|BC| \rightarrow \infty} x_{AB} = 0$$

Limitations and extensions under study

- ◆ Approach is not information-theory based
- ◆ It is packet based
- ◆ In particular, probabilistic unreliable channel is abstracted as a reliable channel of lesser rate
 - “Rate Adaptation”
- ◆ Issues of attacking this very abstraction are not addressed here today

Fundamental ingredients of our approach

- ◆ Standard cryptographic primitives are assumed
 - All packets are encrypted
 - Bad nodes cannot create fake packets, cannot alter good packets without getting caught, etc

- ◆ And, importantly,

- ◆ Clocks and synchronization

Why clocks and synchronization?

- ◆ Without a notion of *time*, we cannot even talk of throughput
 - Without throughput we cannot talk of network Utility
- ◆ So *time* is an essential ingredient

- ◆ Without a notion of *common* time, nodes cannot cooperate temporally
 - They cannot share resources in a time-based way
 - Cooperative scheduling, etc., will be impossible

- ◆ So *synchronization* will be a fundamental ingredient
 - Facilitates temporal cooperation

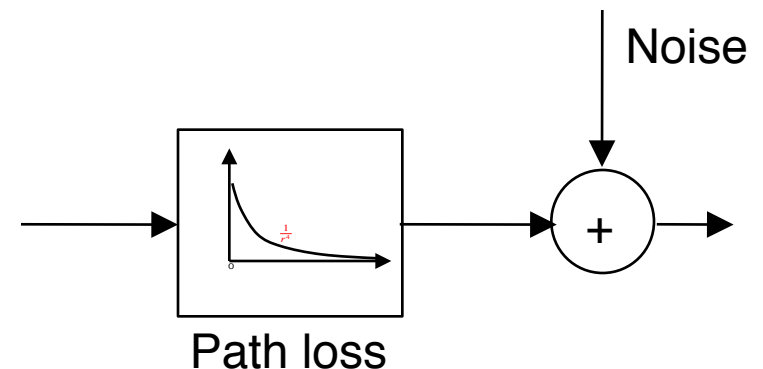
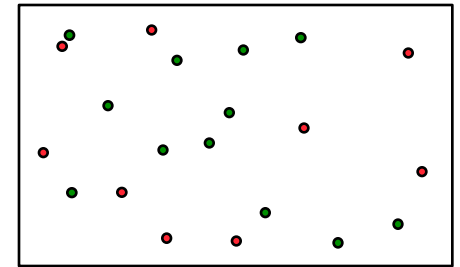
Technical Assumptions (approximately) (1)

- ◆ Bounded domain
- ◆ n nodes, some bad
- ◆ Minimum distance between any pair of nodes
- ◆ Nodes are not mobile

- ◆ Max power constraint at each node
- ◆ Noise at each node

- ◆ Path loss is a function of distance
- ◆ SINR based rate

- ◆ Half-duplex nodes (can relax this)

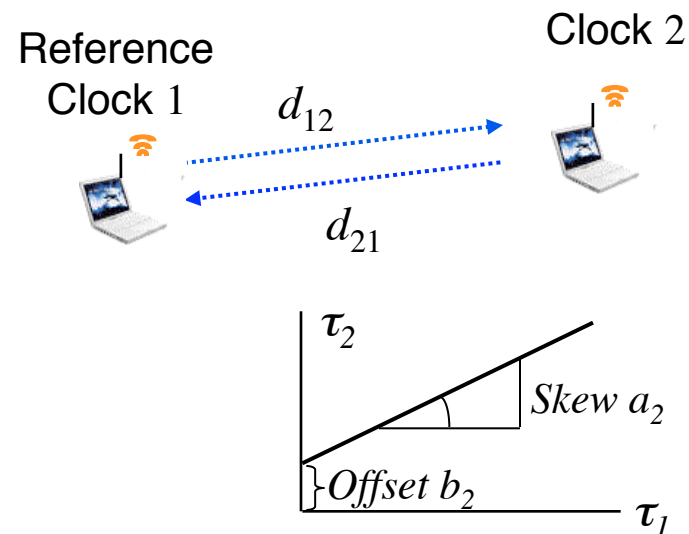


Technical Assumptions (2)

- ◆ Affine clock at each node
 - $0 < 1 - \epsilon \leq \text{Skew} \leq 1 + \delta$ for all nodes

- ◆ Packets take a delay
 d_{ij} from node i to node j

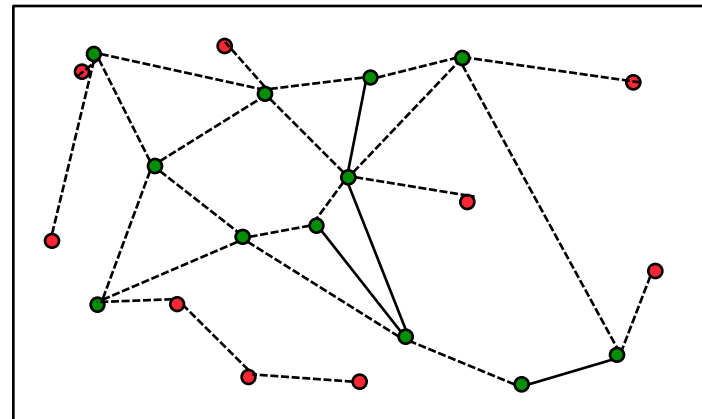
- ◆ Each node has a private key
- ◆ Each node has a certificate which binds a public key to its identity and that is signed by a trusted authority



Technical Assumptions (3)

- ◆ Assumption on connectedness
 - Suppose all nodes transmit at Max power
 - Then suppose there is an edge between each pair of nodes (i, j) an for which SINR_{ij} and SINR_{ji} both exceed $\text{SINR}_{\text{threshold}}$

- Assumptions
 - » Resulting graph is connected
 - » Subgraph of good nodes is also connected



The Approach and Some Issues

- ◆ Nodes need to discover who their neighbors are.
 - Require a two-way handshake between the nodes.
 - How can we guarantee that any two nodes can communicate packets with each other when other nodes are liable to transmit at the same time and cause collisions?
 - Need an orthogonal medium access scheme.
 - Must operate with clocks that are not synchronized but also tick at different and unknown rates.
 - Nodes will need to synchronize their clocks with neighbors.
- ◆ Nodes will need to synchronize their clocks with neighbors.
 - Fundamental limitations to clock synchronization
 - Nodes can synchronize their skews but not their offsets which are indistinguishable from delays.

The Approach and Some Issues (2)

- ◆ Nodes need to form a network.
 - Require network wide consistency checks
 - Everything has to be done in the presence of malicious nodes
- ◆ Nodes draw up a schedule for transmissions and send data.
 - Some malicious nodes that conformed hitherto or remained hidden hitherto may not cooperate.
 - This requires a check to detect malicious behavior and another round of network wide computation with the un-cooperating nodes being taken into account.

The Approach and Some Issues (3)

- ◆ All this also has to be done with a finite bound on clocks and in the presence of skew errors
- ◆ Some challenges when we also aim for ε -optimality over network lifetime.

Phases of protocol (1)

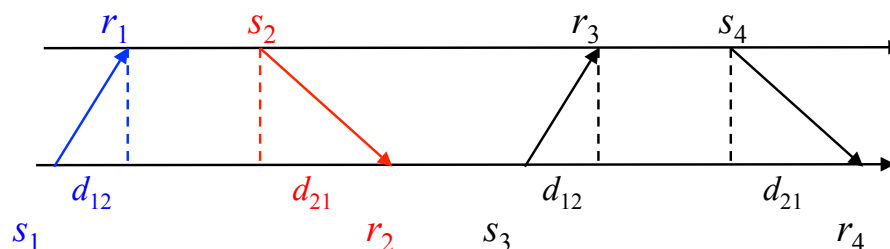
◆ Neighbor Discovery Protocol

- Use orthogonal MAC codes
- Within a bounded time all nodes discover their neighbors

◆ Clock Synchronization Phase

- Pairs of neighboring nodes synchronize clocks

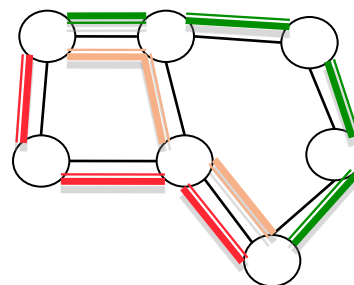
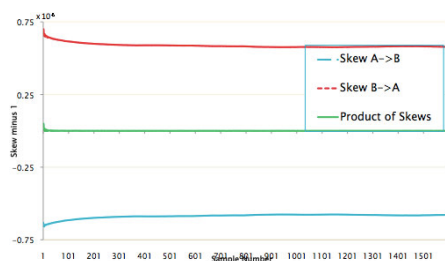
- » Skews can be determined
- » Offsets and one-way delays *cannot* be identified
- » Round trip delays are determined
- » They obtain capability to predict when packet reception times
- » They also identify and certify each end-point and certify state of link



Phases of protocol (2)

- ◆ Route discovery phase
 - Nodes flood the link-states throughout the network
- ◆ Consistency check phase
 - Nodes check that for all cycles

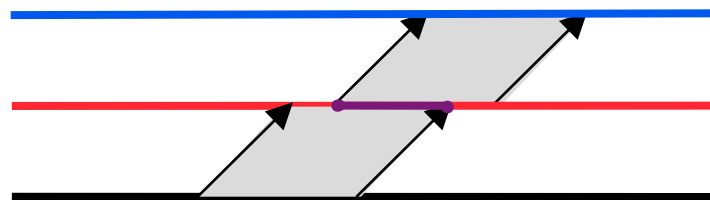
$$\prod_{(i,j) \in \text{Cycle}} \text{Skew}_{ij} = 1$$



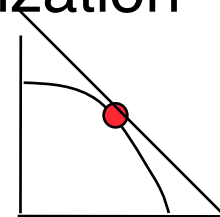
- ◆ At this point
 - All MITMs that are not conforming to consistent timing are caught

Phases of protocol (3)

- ◆ Attack on all half-duplex MITMs
 - Every pair of neighboring nodes sends a long packet that exceeds the round-trip delay



- ◆ Repeat as needed: Nodes have view of the network
 - ◆ Which sets of nodes can concurrently transmit
 - ◆ Link-state including clock-synchronization parameters
- ◆ Choice of operating point for Network Utility Maximization
 - Optimal network resource scheduling is chosen
 - And agreed to by all nodes



Phases of protocol (4)

- ◆ Data transfer phase
 - The nodes send their data
 - » Over the agreed paths
 - » According to the agreed schedule
 - » Relaying taking place according to the schedule
- ◆ Verification of operation
 - Route prefix verification is done to ensure that nodes are conforming
 - Can identify concurrent transmission sets that are not reliable
 - Detected non-conforming concurrent transmission sets are eliminated and network view is established all over again

Thank you